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Beercave racerback tank

The great thing about the Internet is that the cost of getting a new start from the country is usually much less than it would be in the physical world. All you need is an idea, a \$10 domain name and some programmers to help you design the site. But the downside is that today there is even more competition to be noticed, and often there can be an excessive amount of hype when they finally do. In the late 1990s and early 2000s, several internet companies, such as Geocities, were greatly overvalued by investors and eventually fell through, causing many to lose their jobs. Now some publications, including our sister site, TheStreet.com, have begun to speculate that we may be experiencing a second dot-com bubble, as investors are now aggregating new websites like Groupon worth up to \$6 billion and Facebook worth \$50 billion or more. But if the past tells us anything, it's that sites like these can be very popular one day and disappear the next. We rounded up the top 10 websites that have gone from being the next big thing to either shutting down or having bleak futures ahead, and look at the reasons for their demise. Photo Credit: garyknight Skip navigation! Skip navigation! In this Instructables I will show you how to create a simple and effective platform for any Robot project or remote control project. This tank platform is a great base for any robot design as it easily passes through rough terrain. Another big plus with this design can carry a lot of weight for this size. So there is endless possibilities with this design. The engine used by this platform can be controlled by any means. I use a cheap RC car to control the engines. The gearbox and engine combination can provide different gear ratio settings for your application set. The gear ratio I use is 114.7:1 @ 4.5V. This ratio works well with the remote control I use. I have to try other ratios, but do it through heat transistors on the RC board. This Tank platform uses two engines, so it uses sheer steering to turn. So you need at least you need two RC car channels to make this project, but most RC car has at least two channels as well. I'll show you the new and the old design. The old design will be known as the Mk1 and the new Mk2.I design got all the parts for this platform from Jaycar Electronics.Jaycar Electronics. I got the RC car from the local market for a few dollars. LIST OF PARTS 1. Twin-engine independent four-speed gearbox/axle assembly Tamiya ITEM 70097 Jaycar Cat No. YG2741 \$22.95 2. Tamiya Track & Wheel Set (Need two if you want to build an Mk2) Jaycar Cat No. YG2867 \$16.95 3. 2 X Tamiya Universal Board Set Jaycar Cat No. YG2865 \$8.95 4. M3 stand off posts 25mm Jaycar Cat No HP0907 \$5.95 5. M3 Screws Jaycar Cat No. HP0400 \$2.50 6. M3 Nuts Jaycar Cat No HP0425 \$2.95 7. Cable ties Jaycar Cat No. HP1200 \$1.85 8. 3 from 1 AA battery holders Jaycar Cat No. PH9203 \$0.95 9. the car everyone will make mine cost me \$20 to \$10. On/off Jaycar Cat No. ST0300 \$2.95 All prices in AUS\$ TOOLS 1. Philips screwdriver 2. 2. 3. Pliers 4. Soldering game 5. Knife I have a cheap RC car from the local market. I pull apart to find a nice layout of components on board. Clearly mark also so it will be a great help when plugging in the engines and battery. The control board has two wires that go from the steering motor and the drive motor. These will get to the new engine in our gearbox. I put left and right signals on the right engine; back and forth to the left engine. When you turn on the board, you may find that the engine is going the wrong way just swap around two wires to go to the engine. There are other ways to power and drive these two engines, but this is a simple and fun way to do it. Now we have a board to remove from our RC car that I got from the markets. We need to tap into our new transmission and the engines that power the tracks. RC boards are a two-channel receiver. So the steering engine that went to drive the car forward and back will go to the left engine on our new transmission. The first step in this project is the construction of the gearbox and the assembly of the engine. I supply the photo with which the gearbox was supplied. The gear ratio I use is 114.7:1 @ 4.5 volts. As long as you follow the step of the list below in the photo you will be fine. I recommend that when using this gearbox for a long time or over sand or dirty terrain, which uses some machine oil to re-lubricate the gearbox. Since the devices are exposed to the elements. Making a motherboard, all I did is to set the base using a pair of side cutters. Here sits the engine and gearbox. You then connect the gearbox and engine to the platform using the screws supplied by the kit. I bought two Tamiya Universal Plate Set. So I have enough screw and other pieces and pieces to build this new design Mk 2. I also needed two wheels and the track set to build the Mk 2.Mk2 is a bit more complicated. You need four right angular flanges. Those two are cut open, so you can fit another couple of road bikes. Then I screw them to the base, then idling the wheel flange to get the screw to the base as well. I use extra wheels in the second set to make enough wheels for this new design. I use four pairs of road bikes. The idling bike is the same size as the rear sprocket and road bikes. Now it's both salary form. Then you insert four bars into the right angular flange. Then you install three larger road bikes. Then repeat for an idling bike that uses as big a bike as road bikes. The sprocket is then placed on the engine output shaft. The Mk1 is simple in design, using only three road bikes. Assembled road bikes differ from Mk 1. You only need one universal set of Tamiya boards. Because you only need three pairs of road bikes. Screw the right angular flange to the platform. Then you screw the front idling bike assembled on to the platform. Then you insert four bars into the right angular flange. You then install three road bikes. Then repeat for the idling bike that uses the largest wheel in the set. The sprocket is then placed on the engine output shaft. Now we're entering the tracks. This process is an attempt error until I was happy with the tension of the tracks you want some game so they don't fall off when turning and go over obstacles. I pointed to the first photo, what length of track you need for Mk1 then in the second photo, what tracks you need for Mk2.All you do is place the card inside the hole of other tracks. Then you repeat until it is carried out along the entire length of the track. Then you place the track over the idle wheel and the chain wheel. Then you get to the track around the road bikes. Then check if the track has enough to play in them. Their installation is easy. I'll place the tracks above the drive chain wheel and the idling wheel. Then he grabs the bottom of the track and pulls under the wheels. After I install both sets of songs. I'm just checking the track voltage. As shown below, this track has passed. You can move the engine and gearbox forward or backward to increase or decrease the voltage on the tracks. I use three simple AA batteries to give me a 4.5 volt for the control board. All I do is tie them to the platform with a cable. Then cut the excess on the underside of the platform. You can wire three AA batteries together in a series and install on/off on the positive side that will be on the control board. Then look with some fresh battery that you have 4.5 to come out of the battery using the voltmeter. I had to postpone because the new control board was bigger than I thought. So this battery is on the roof of the platform tank. Then take the entire roof part to get the screw on this stand off. Driving this tank has a little skill. How to use the shed steering turn if you want to turn right to let go of the left engine control switch. When they want the left turn to let go of the right engine control switch. When moving forward, you must move both control switches forward. But after a while, you get used to driving a tank. Here are some photos of the tank out and about. Thanks for viewing my instructable. Skip navigation! You can't win this. Self-service is none of our business. When it comes to pilot fish, very little shocks them. It's not the best decision ever made. I don't think she was clear on the concept. But you demo it that way. It's a whole new category of PC abuse. The legal mind at work. No good deed will go unpunished. Brute force is rarely a good idea in the field of computing. He always gets up on the wrong side of the bed. I don't think you understand my question very well. But it's a good lesson in humility. I think I met all the requirements perfectly. Logic will only take you so far, my dear Watson. It's a whole new world in this place. Speed is so relative. You could have told us that a week ago. Simple math stumps computer system. They always say that if you want to do the right job... Load more more

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